

Effects of Axial Imperfections on Vibrations of Anti-Symmetric Cross-Ply, Oval Cylindrical Shells

David Hui

Assistant Professor,
Mem. ASME

I. H. Y. Du

Graduate Student.

Department of Engineering Mechanics,
The Ohio State University,
Columbus, Ohio 43210

This paper examines the effects of axial geometric imperfections on the fundamental vibration frequencies of cross-ply simply-supported oval cylindrical shells. It is found that the presence of such imperfection with small amplitudes may significantly raise or lower the fundamental frequencies, depending on the wave numbers of the imperfection and vibration mode. The effects of oval eccentricity, bending-stretching coupling of the material, the reduced-Batdorf parameter and Young's moduli ratio are examined. It appears that the present problem has not been examined, even in the simplified case of oval cylindrical shells made of isotropic-homogeneous material.

1 Introduction

The effects of geometric imperfections on the vibration frequencies of isotropic-homogeneous shells have been thoroughly analyzed by a number of researchers. For example, the influence of geometric imperfections on circular cylindrical shells were examined by Rosen and Singer (1974, 1976), Koval'chuk and Krasnopol'skaya (1980), Singer and Prucz (1982), and Watawala and Nash (1983). Similar analyses on open, simply-supported, cylindrical panels within plane constraints (Hui 1984), shallow spherical shells segments (Hui and Leissa, 1983, and Hui, 1983) have also been reported. However, all of these studies have been concerned with isotropic-homogeneous materials.

The influence of geometric imperfections on the fundamental frequencies of anti-symmetrically angle or cross-ply rectangular plates were examined by the author (Hui 1985a, b). Further analyses of anti-symmetric angle-ply simply-supported cylindrical panels were performed by Du and Hui (1984). More complicating effects involving elastically restrained edges and elastic foundation were also studied by Bhattacharya (1984); however, his analysis was restricted to symmetrically laminated cylindrical panels. The effects of general imperfections (that is, not necessarily the same shape as the vibration mode) on vibrations of laminated circular cylindrical shells using the finite element method were studied by Yang and Kapania (1985) and Kapania and Yang (1986). Due to storage and maneuverability requirements of aircraft

fuselages, submarine hulls, and cylindrical tanks, it is of interest to examine the effects of noncircularity on vibrations of cylindrical shells. This problem is also of interest to the basic applied mechanics community since it appears that the effects of imperfections on even the isotropic-homogeneous oval shells has not been previously reported. In passing, vibrations of "perfect isotropic-homogeneous" noncircular cylindrical shells were examined by Malkina (1967), Sewell et al. (1971), Culberson and Boyd (1971), Chen and Kempner (1978), Koumouis and Armenakas (1983), and Suzuki and Leissa (1985), among others. Vibrations of "perfect-laminated" oval cylindrical shells were examined by Sathyamoorthy and Pandalai (1970), Soldatos and Tzivanidis (1982), and Soldatos (1983, 1984, 1985).

The present analysis is based on a solution of Donnell-type linearized equilibrium and compatibility equations of laminated oval cylindrical shell. The shell is assumed to be simply supported with no in-plane shear load and no axial load at both ends. The compatibility equation is satisfied exactly by an appropriate choice of the stress function and the equilibrium equation is satisfied approximately by a Galerkin procedure. Thus, the computed frequencies are "upper-bounds." An iterative inverse power method is used to solve for the smallest eigenvalue. The fundamental frequencies are obtained by solving for the smallest eigenvalue for all possible axial wave number and circumferential boundary conditions.

In order to simplify the analysis, the geometric imperfection of the oval cylinders are assumed to be axisymmetric (that is, no circumferential waves). The number of waves in the axial direction of the geometric imperfections need not be the same as that for the vibration mode. Thus, two possibilities arise: if the effects of axial imperfection are found to affect significantly the fundamental frequencies, then one cannot safely neglect the effects of "general" imperfections which occur in practice. On the other hand, if these effects are not important, then no conclusion can be drawn about the effects of "general" imperfections.

Contributed by the Applied Mechanics Division for presentation at the Winter Annual Meeting, Anaheim, CA, December 7-12, 1986, of The American Society of Mechanical Engineers.

Discussion on this paper should be addressed to the Editorial Department, ASME, United Engineering Center, 345 East 47th Street, New York, N.Y. 10017, and will be accepted until two months after final publication of the paper itself in the JOURNAL OF APPLIED MECHANICS. Manuscript received by ASME Applied Mechanics Division, November 8, 1985; final revision, April 4, 1986. Paper No. 86-WA/APM-36.

2 Vibrations of Oval Cylindrical Shells

The vibration analysis is based on a solution of Donnell-type equilibrium and compatibility equations for "generally" laminated oval cylindrical shells, written in terms of an out-of-plane deflection W , the stress function F , incorporating the possibility of an axisymmetric (that is, axial) geometric imperfection W_o . They are, respectively,

$$\rho W_{,\bar{t}\bar{t}} + L_D^*(W) + L_B^*(F) + (1/R(Y))(F_{,XX}) = F_{,YY}(W + W_o)_{,XX} + F_{,XX}W_{,YY} - 2F_{,XY}W_{,XY} \quad (1)$$

$$L_A^*(F) = L_B^*(W) + (W_{,XY})^2 - (W + W_o)_{,XX}W_{,YY} + [1/R(Y)]W_{,XX} \quad (2)$$

In the above equations, X and Y are the axial and circumferential coordinates, ρ is the mass of the shell per unit surface area, \bar{t} is time, and $R(Y)$ is the variable radius of the oval cylindrical shell. The linear differential operators $L_A^*(\cdot)$, $L_B^*(\cdot)$ and $L_D^*(\cdot)$ are defined by Tennyson et al. (1971) and they are defined later in nondimensional form in equations (9). Further, each layer is orthotropic and (A_{ij}, B_{ij}, D_{ij}) and $(A_{ij}^*, B_{ij}^*, D_{ij}^*)$ are defined to be, (Ashton et al. 1969),

$$(A_{ij}, B_{ij}, D_{ij}) = \sum_{k=1}^n (\bar{Q}_{ij})_k (h_k - h_{k-1}, h_k^2 - h_{k-1}^2, h_k^3 - h_{k-1}^3) \quad (3a)$$

$$[A_{ij}^*] = [A_{ij}]^{-1}, [B_{ij}^*] = -[A_{ij}]^{-1}[B_{ij}], [D_{ij}^*] = [D_{ij}] - [B_{ij}][A_{ij}]^{-1}[B_{ij}] \quad (3b)$$

Note that for the k th layer, the principal stresses are related to the principal strains such that $[\sigma_1, \sigma_2, \tau_{12}]^T = [Q_{ij}][\epsilon_1, \epsilon_2, \gamma_{12}]^T$; where $Q_{16} = 0, Q_{26} = 0$ for the above mentioned orthotropic lamina. For an arbitrary set of axes in the k th layer, $[\sigma_x, \sigma_y, \tau_{xy}]^T = [\bar{Q}_{ij}][\epsilon_x, \epsilon_y, \gamma_{xy}]^T$ where $\bar{Q}_{11}, \bar{Q}_{22}, \bar{Q}_{12}, \bar{Q}_{66}$ are even functions of the fiber angle while $\bar{Q}_{16}, \bar{Q}_{26}$ are odd functions of the fiber angle.

The following nondimensional quantities are introduced,

$$(a_{ij}^*, b_{ij}^*, d_{ij}^*) = (E_2 h A_{ij}^*, B_{ij}^*/h, D_{ij}^*/(E_2 h^3)) \\ (x, y) = (X, Y)/(R_o h)^{1/2} \\ (w, w_o) = (W/h, W_o/h), f = F/(E_2 h^3) \\ t = \omega_r \bar{t}, (\omega_r)^2 = E_2 h / (\rho R_o^2) \quad (4)$$

where ω_r is the reference frequency, h is the total thickness of the laminated shell, E_2 is Young's modulus of a particular layer in the transverse direction, and the average radius of the oval cylindrical shell R_o can be obtained from,

$$\int_{\theta=0}^{2\pi} R(Y) d\theta = 2\pi R_o \quad (5)$$

Thus, the nondimensional linearized Donnell-type equilibrium and compatibility equations for laminated oval cylindrical shell becomes,

$$w_{,tt} + L_d^*(w) + L_b^*(f) + [1/r(y)]f_{,xx} = w_{o,xx}f_{,yy} \quad (6)$$

$$L_a^*(f) = L_b^*(w) + [1/r(y)]w_{,xx} - w_{o,xx}w_{,yy} \quad (7)$$

where ϵ is the oval eccentricity parameter and $r(y) = R(y)/R_o$ can be obtained from (see Chen and Kemper, 1971, and Soldatos, 1984),

$$1/r(y) = 1 + \epsilon \cos(2Y/R_o) \quad (8)$$

For an antisymmetric cross-ply laminate, the nondimensional linear operators are defined to be (Hui, 1986),

$$L_a^*(\cdot) = a_{22}^*(\cdot)_{,xxxx} + (2a_{12}^* + a_{66}^*)(\cdot)_{,xxyy} + a_{11}^*(\cdot)_{,yyyy}$$

$$L_b^*(\cdot) = b_{21}^*(\cdot)_{,xxxx} + (b_{11}^* + b_{22}^* - 2b_{66}^*)(\cdot)_{,xxyy} + b_{12}^*(\cdot)_{,yyyy} \\ L_d^*(\cdot) = d_{11}^*(\cdot)_{,xxxx} + (2)(d_{12}^* + 2d_{66}^*)(\cdot)_{,xxyy} + d_{22}^*(\cdot)_{,yyyy} \quad (9)$$

The axial geometric imperfection and the vibration mode are assumed to be of the form,

$$w_o(x) = \mu \sin(Jx) \quad (10a)$$

$$w(x, y) = w(y) \sin(Mx) \quad (10b)$$

In the above, μ is the amplitude of the imperfection and the wave number J and M are defined in terms of the reduced-Batdorf parameter Z_H by,

$$(J, M) = (j\pi/Z_H, m\pi/Z_H), Z_H = L/(R_o h)^{1/2} \quad (11)$$

where the integers j and m are number of axial half-waves.

It can be seen from the compatibility equation that the analysis would be much simpler if the stretching-twisting coupling coefficients vanish so that from now on, $a_{16}^* = 0, a_{26}^* = 0$. This restriction means that for each layer of a plus-positive fiber angle, there exists another layer of the same orthotropic properties and thickness with a negative fiber angle since \bar{Q}_{16} and \bar{Q}_{26} are odd function of the fiber angle. Thus, the stress function which satisfies the linearized compatibility equation exactly is,

$$f(x, y, t) = f_A(y) \sin(Mx) + f_B(y) \cos(Mx) + f_C(y) \cos[(J-M)x] + f_D(y) \cos[(J+M)x] + (c_x)(x^2/2) + (c_y)(y^2/2) \quad (12)$$

For ordinary differential equations are obtained from this compatibility equation by collecting terms involving $\sin(Mx), \cos(Mx), \cos[(J-M)x]$, and $\cos[(J+M)x]$, respectively:

$$a_{11}^* f_A(y)_{,yyyy} + (-M^2)(2a_{12}^* + a_{66}^*)f_A(y)_{,yy} + M^4 a_{22}^* f_A(y) = b_{12}^* w(y)_{,yyyy} - M^2 (b_{11}^* + b_{22}^* - 2b_{66}^*)w(y)_{,yy} + [b_{21}^* M^4 - (M^2/r(y))]w(y) \quad (13)$$

$$a_{11}^* f_B(y)_{,yyyy} + (-M^2)(2a_{12}^* + a_{66}^*)f_B(y)_{,yy} + M^4 a_{22}^* f_B(y) = (2b_{26}^* - b_{61}^*)(-M^3)w(y)_{,y} + (2b_{16}^* - b_{62}^*)(M)w(y)_{,yyy} \quad (14)$$

$$a_{11}^* f_C(y)_{,yyyy} - (J-M)^2(2a_{12}^* + a_{66}^*)f_C(y)_{,yy} + (J-M)^4 a_{22}^* f_C(y) = (\mu J^2/2)w(y)_{,yy} \quad (15)$$

$$a_{11}^* f_D(y)_{,yyyy} - (J+M)^2(2a_{12}^* + a_{66}^*)f_D(y)_{,yy} + (J+M)^4 a_{22}^* f_D(y) = (-\mu J^2/2)w(y)_{,yy} \quad (16)$$

The remaining ordinary differential equation can be obtained from the linearized equilibrium equation using a Galerkin procedure (that is, multiplying both sides by $\sin(Mx)$ and integrating from $x=0$ to $x=Z_H$),

$$\{ -(\omega/\omega_r)^2 w(y) + d_{22}^* w(y)_{,yyyy} - 2M^2(d_{12}^* + 2d_{66}^*)w(y)_{,yy} + d_{11}^* M^4 w(y) + b_{12}^* f_A(y)_{,yyyy} + (b_{11}^* + b_{22}^* - 2b_{66}^*)(-M^2)f_A(y)_{,yy} + [b_{21}^* M^4 - (M^2/r(y))]f_A(y) - M(2b_{16}^* - b_{62}^*)f_B(y)_{,yyy} + (M^3)(2b_{26}^* - b_{61}^*)f_B(y)_{,y} + (1/2) + \{ b_{12}^* f_C(y)_{,yyyy} - (b_{11}^* + b_{22}^* - 2b_{66}^*)(J-M)^2 f_C(y)_{,yy} + [(J-M)^4 b_{21}^* - (M^2/r(y))]f_C(y) \} I_1 + \{ b_{12}^* f_D(y)_{,yyyy} - (b_{11}^* + b_{22}^* - 2b_{66}^*)(J+M)^2 f_D(y)_{,yy} + [(J+M)^4 b_{21}^* - (M^2/r(y))]f_D(y) \} I_2 = (I_3)(-J^2 \mu) f_A(y)_{,yy} \quad (17)$$

where the definite integrals $I_1, I_2,$ and I_3 are defined to be,

$$I_1 = (1/Z_H) \int_{x=0}^{Z_H} \cos[(J-M)x] \sin(Mx) dx = [1/(2Z_H)] \{ (-2/J) + [2/(J-2M)] \} \text{ if } j \text{ is odd;} \\ 0 \text{ otherwise} \quad (18)$$

$$I_2 = (1/Z_H) \int_{x=0}^{Z_H} \cos[(J+M)x] \sin(Mx) dx$$

$$= [1/(2Z_H)] \{ [-2/(J+2M)] + (2/J) \} \text{ if } j \text{ is odd;} \\ 0 \text{ otherwise} \quad (19)$$

$$I_3 = (1/Z_H) \int_{x=0}^{Z_H} \sin[(Jx) \sin^2(Mx) dx$$

$$= [1/(2Z_H)] \{ (-2/J) + [1/(J+2M)] + [1/(J-2M)] \} \\ \text{if } j \text{ is odd;} \\ 0 \text{ otherwise} \quad (20)$$

The above five coupled ordinary homogeneous differential equations with five variables $f_A(y)$, $f_B(y)$, $f_C(y)$, $f_D(y)$ and $w(y)$ are discretized using a central finite difference scheme. Due to symmetry considerations, the deflection and the stress function of the oval cylindrical shell must be either symmetric or antisymmetric at the semi-major ($Y=0$) and the semi-minor ($Y=\pi R_o/2$) axes. Thus, only one-quarter of the shell needs to be discretized. Further, the deflection mode can be identified as one of the following four groups: *SS* (symmetric at both axes), *AA* (antisymmetric at both axes), *SA* (symmetric at the semi-major axis and antisymmetric at the semi-minor axis), and *AS* (antisymmetric at the semi-major axis and symmetric at the semi-minor axis). Thus, the boundary conditions at either the semi-major axis ($Y=0$) or the semi-minor axis ($Y=\pi R_o/2$) for the symmetric mode are (Hutchinson 1968),

$$w_{,y} = 0, w_{,yyy} = 0, \\ f_{A,y} = 0, f_{B,y} = 0, f_{C,y} = 0, f_{D,y} = 0, \\ f_{A,yyy} = 0, f_{B,yyy} = 0, f_{C,yyy} = 0, f_{D,yyy} = 0 \quad (21)$$

For the antisymmetric mode, the boundary conditions are,

$$w = 0, w_{,yy} = 0, \\ f_A = 0, f_B = 0, f_C = 0, f_D = 0, \\ f_{A,yy} = 0, f_{B,yy} = 0, f_{C,yy} = 0, f_{D,yy} = 0 \quad (22)$$

The out-of-plane simply-supported boundary conditions are satisfied exactly by the choice of the mode shape. The zero in-plane shear stress condition is also satisfied identically at the two ends of the cylindrical shell. The zero axial stress and zero lateral pressure conditions are also satisfied approximately by setting $c_x = 0$, $c_y = 0$. The total number of circumferential full-waves is defined to be \bar{n} and is equal to half the number of nodal points of the deflection mode in a complete circumferential circuit. The symbol n is not used in this paper (\bar{n} refers to the finite difference mode shape and n refers to the trigonometric modes used by Soldatos, 1984). Due to singlevaluedness and continuity of the displacements and slopes, the *SS* and *AA* modes correspond to \bar{n} being even and the *AS* and *SA* mode correspond to \bar{n} being odd.

The above five coupled ordinary differential equations and the associated boundary conditions can be discretized and these constitute the eigenvalue problem of the form,

$$[A]\bar{x} = \omega[B]\bar{x} \quad (23)$$

where $[A]$ is a banded matrix with bandwidth 23, $[B]$ is a diagonal matrix, and \bar{x} is the solution vector. For a given axial wave number m , the smallest eigenvalue is obtained using the inverse power method (Hui and Hansen, 1982) in conjunction with the use of the linear equation solver LINPACK (Dongarra et al., 1979). As expected, the fundamental frequencies of imperfect oval cylinders generally correspond to one axial half wave ($m=1$) in the vibration mode.

3 Discussion of Results

Due to numerous material parameters involved in a laminated shell structure, all the example problems are

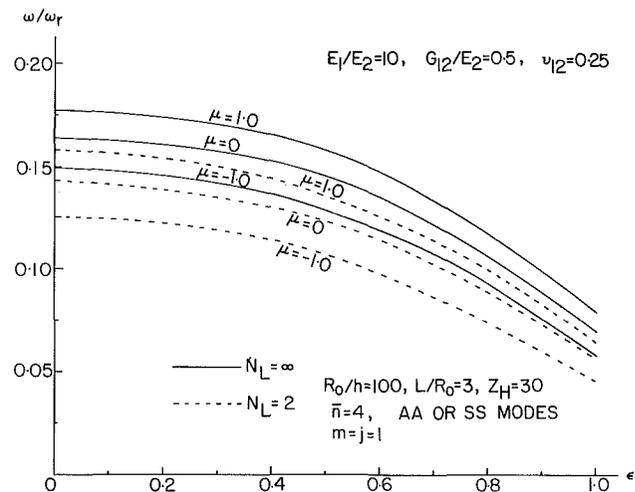


Fig. 1(a) Fundamental frequency versus the eccentricity parameter for anti-symmetric cross-ply Boron-epoxy, simply-supported oval cylindrical shells (*SS* and *AA* modes with \bar{n} = even)

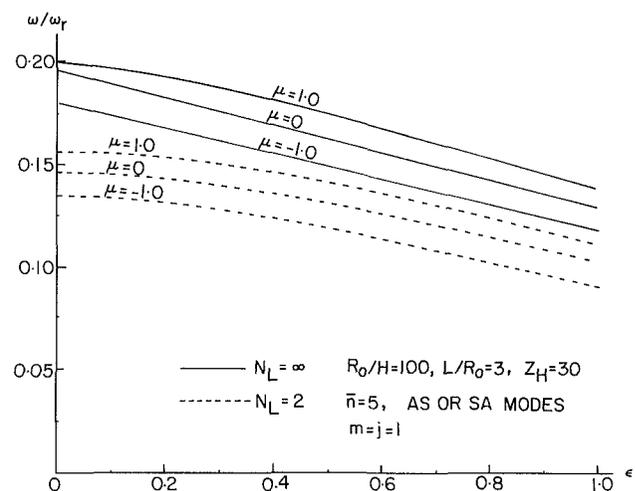


Fig. 1(b) Fundamental frequency versus the eccentricity parameter for anti-symmetric cross-ply Boron-epoxy, simply-supported oval cylindrical shells (*SA* and *AS* modes with \bar{n} = odd)

restricted to antisymmetric (even number of equal-thickness layers and each layer is orthotropic) cross-ply oval cylindrical shells made of Boron-epoxy material where (Soldatos, 1984),

$$E_1/E_2 = 10, G_{12}/E_2 = 0.5, \nu_{12} = 0.25, \nu_{21} = \nu_{12}E_2/E_1 \quad (24)$$

This implies zero stretching-twisting coupling so that $A_{16} = 0$, $A_{26} = 0$ ($A_{16}^* = 0$, $A_{26}^* = 0$), zero bending-twisting coupling so that $D_{16} = 0$, $D_{26} = 0$ ($D_{16}^* = 0$, $D_{26}^* = 0$). Further $B_{16} = 0$, $B_{26} = 0$ ($B_{16}^* = 0$, $B_{26}^* = 0$, $B_{61}^* = 0$, $B_{62}^* = 0$) and the nonzero bending-stretching coupling coefficients are B_{11} , B_{12} , B_{21} , B_{22} , and B_{66} .

Figure 1(a) shows a graph of the nondimensional fundamental frequency ω/ω_r versus the oval eccentricity parameter ϵ for antisymmetric, Boron-epoxy cross-ply oval cylindrical shells simply-supported at both ends. The number of layers N_L is infinite ($b_{ij}^* = 0$) or two ($b_{ij}^* \neq 0$) as shown in solid or dotted lines, respectively. The geometric parameters are

$$R_o/h = 100, L/R_o = 3, Z_H = 30 \quad (25)$$

for a fixed value of \bar{n} being an even integer, there exists a negligible difference in the fundamental frequencies between the *AA* and *SS* modes because their mode shapes are almost identical in shape except for a phase shift in the circumferential direction. The maximum fundamental frequency cor-

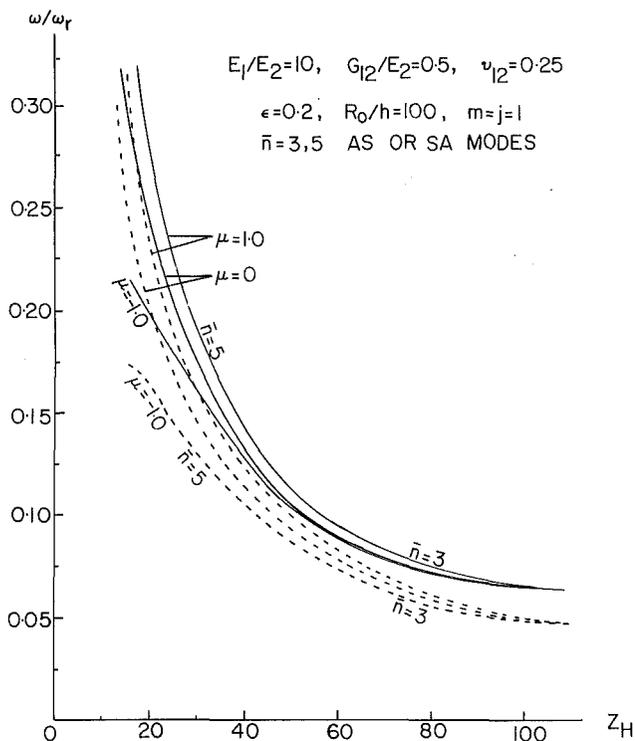


Fig. 2(a) Fundamental frequency versus the reduced-Batdorf parameter for cross-ply Boron-epoxy, simply-supported oval cylindrical shells (SS and AA modes with \bar{n} = even)

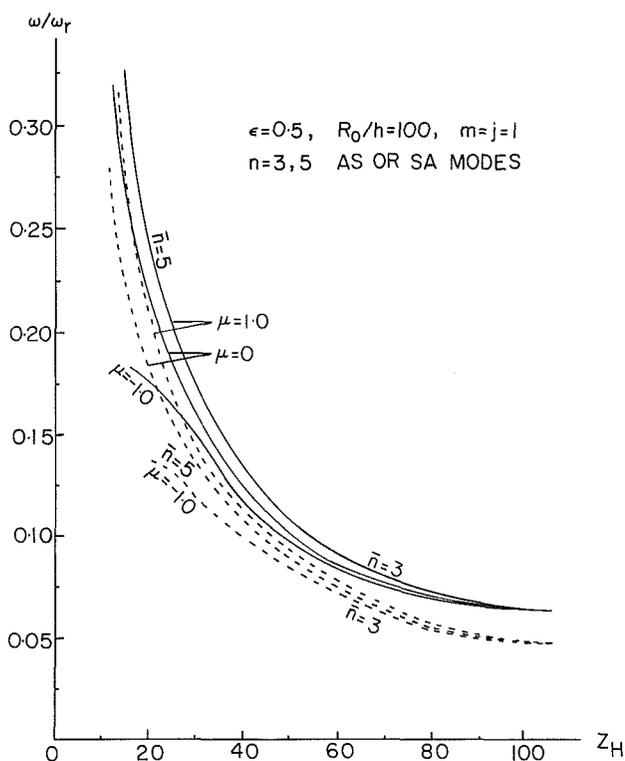


Fig. 2(b) Fundamental frequency versus the reduced-Batdorf parameter for cross-ply Boron-epoxy, simply-supported oval cylindrical shells (SA and AS modes with \bar{n} = odd)

responds to a circular cylindrical shell ($\epsilon = 0$) and the frequencies decrease monotonically as the oval eccentricity ϵ increases. It can be seen that the presence of small axial geometric imperfection with one axial half wave ($j=1$) may significantly

raise or lower the fundamental frequencies for $\mu=1$ and $\mu=-1$, respectively. For positive imperfection amplitude, the shell bulges outwards prior to vibration, causing an additional increase of the curvature, and thus an increase of the fundamental frequencies. On the other hand, for negative values of the imperfection amplitudes, the shell bulges inwards causing a reduction of the curvature of the shell and thus a reduction of the frequencies. Significant reductions in the fundamental frequencies are found due to bending-stretching coupling by comparing the $N_L = \text{infinite}$ and $N_L = 2$ curves.

The above effects of the geometric imperfections were qualitatively similar to the vibration behavior of simply supported cylindrical panels (Hui, 1984). Note that for even axial wave number ($j=m=\text{even}$), the frequency of this nonfundamental mode does not depend on the sign of the imperfection amplitude. As a check on the analysis, the fundamental frequencies of the special case of a "perfect-laminated" and "perfect-isotropic homogeneous" simply-supported oval cylindrical shells agree with that presented by Soldatos (1984) and Kempner and Chen (1978), respectively.

The fundamental frequencies of the SA and AS modes are also indistinguishable and they correspond to $\bar{n}=5$ as shown in Fig. 1(b), using the same material and geometric parameters as in Fig. 1(a).

Figure 2(a) shows a plot of fundamental frequency ($m=1$) versus the reduced Batdorf parameter Z_H for antisymmetric cross-ply, simply-supported oval cylindrical shells for the AS and SA modes ($\bar{n} = 3$ or 5). The following geometric parameters are kept fixed:

$$R_o/h = 100, \quad \epsilon = 0, \quad m = j = 1 \quad (26)$$

It can be seen that the presence of axial imperfections ($j=1$) has very little effect on the fundamental frequencies for a large reduced Batdorf parameter ($Z_H = 70$). On the other hand, they may significantly increase or decrease the fundamental frequencies for a small reduced Batdorf parameter. The value of \bar{n} becomes smaller for a larger reduced Batdorf parameter. Note that a large reduced Batdorf parameter corresponds to a longer or thinner shell. Comparing the $N_L = \text{infinite}$ and $N_L = 2$ curves, significant reductions of the fundamental frequencies are seen to occur (due to bending-stretching coupling of the laminated shell) especially for a smaller reduced Batdorf parameter. Again, a positive imperfection amplitude raises the fundamental frequency while a negative value lowers it. The effects of the geometric imperfections diminish as the reduced Batdorf parameter increases.

A similar plot of the fundamental frequency versus the reduced Batdorf parameter for a larger oval eccentricity ϵ being 0.5 is presented in Fig. 2(b). The above discussions in Fig. 2(a) are also applicable in Fig. 2(b). However, for negative imperfection amplitude μ being -1.0 , the fundamental frequency increases very slowly as the reduced Batdorf parameter is decreased. It actually reaches a peak at Z_H being approximately 20 and the frequency actually drops for smaller Z_H (not shown as this may be due to numerical instability).

Figure 3 shows a graph of the fundamental frequency versus the axial imperfection amplitude for antisymmetric cross-ply oval cylindrical shells. Only the SA and AS modes ($\bar{n}=3, 7$) are considered because the SA and AA modes ($\bar{n}=\text{even}$) behave qualitatively in a similar way. The following parameters are held fixed:

$$R_o/h = 100, \quad \epsilon = 0.2 \quad (27)$$

It is found that the fundamental frequencies is significantly affected by the presence of an axial ($j=1$) geometric imperfection for the reduced Batdorf parameter ($Z_H=10$). However, the fundamental frequencies are relatively insensitive to axial geometric imperfection for a larger reduced Batdorf parameter ($Z_H=40$ and $Z_H=70$) for $N_L=2$. For comparison

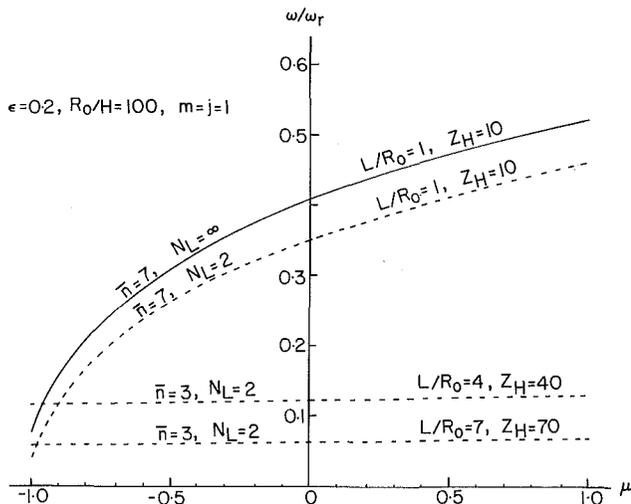


Fig. 3 Fundamental frequency versus the axial imperfection amplitude for cross-ply Boron-epoxy, simply-supported oval cylindrical shells (AS and AS modes with $\bar{n} = \text{odd}$)

purposes, the curves for the orthotropic shell ($N_L = \text{infinite}$) with $L/R_0 = 1$, $Z_H = 10$, is also plotted in (solid lines).

Figure 4(a) shows a plot of the fundamental frequency versus Young's moduli ratio for antisymmetric cross-ply, simply-supported, oval cylindrical shells for the SS and AA modes ($\bar{n} = \text{even}$). The fundamental frequencies for the SS and AA modes are almost identical. The frequencies increase with Young's moduli ratio and the increase in frequencies is slightly more pronounced for the orthotropic ($N_L = \text{infinite}$) than the $N_L = 2$ shell. Clearly, for $E_1/E_2 = 1$ (that is, for isotropic-homogeneous shell) the $N_L = \text{infinite}$ and $N_L = 2$ curves coincide. A similar graph for the AS and SA modes ($\bar{n} = \text{odd}$) is presented in Fig. 4(b) and the above comments are also qualitatively applicable to these modes. As predicted by Soldatos (1984), there exist negligible differences between the $\bar{n} = \text{odd}$ and $\bar{n} = \text{even}$ frequency curves.

4 Concluding Remarks

The influence of axial geometric imperfections on the fundamental vibration frequencies of cross-ply simply-supported oval cylindrical shells has been studied. The presence of such imperfection amplitudes of the order of the shell thickness may significantly raise or lower the fundamental frequencies, depending on the imperfection and the vibration mode wave numbers. Parameter variations involving the oval eccentricity, the number layers, the reduced-Batdorf parameter, and Young's moduli ratio were examined.

Acknowledgments

The authors would like to acknowledge the financial support provided by OSU Office of Research and Graduate Studies. The generous use of the ADML computer facilities is also greatly appreciated.

References

- Ashton, J. E., Halpin, J. C., and Petit, P. H., 1969, *Primer on Composite Materials: Analysis*, Technomic Publishing Co., Westport, 130 pp.
- Bhattacharya, A. P., 1984, "Large Amplitude Vibrations of Imperfect Cross-Ply Laminated Cylindrical Shell Panels with Elastically Restrained Edges and Resting on Elastic Foundation," *Fibre Science and Technology*, Vol. 21, pp. 205-221.
- Chen, Y., and Kempner, J., 1978, "Modal Method for Free Vibration of Oval Cylindrical Shells with Simply Supported or Clamped Edges," *ASME JOURNAL OF APPLIED MECHANICS*, Vol. 45, pp. 142-148; detailed version appeared as Polytechnic Institute of New York, Poly-AE/AM Report No. 75-14, Aug. 1975.

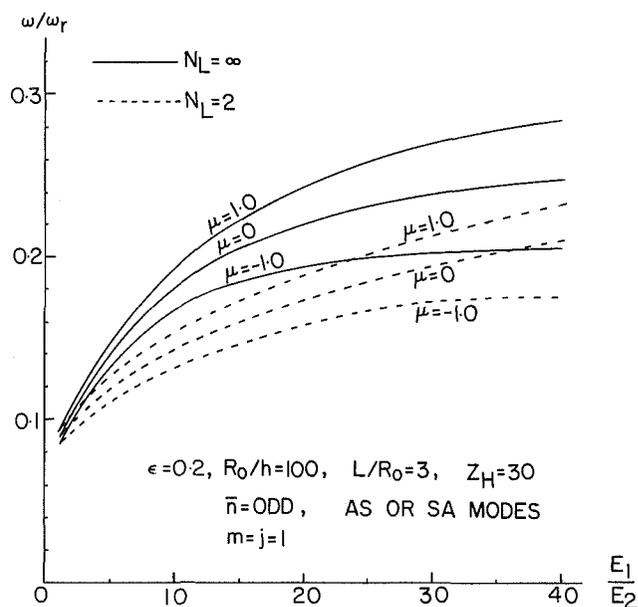


Fig. 4(a) Fundamental frequency versus Young's Moduli ratio for cross-ply Boron-epoxy, simply-supported oval cylindrical shells (SS and AA modes with $\bar{n} = \text{even}$)

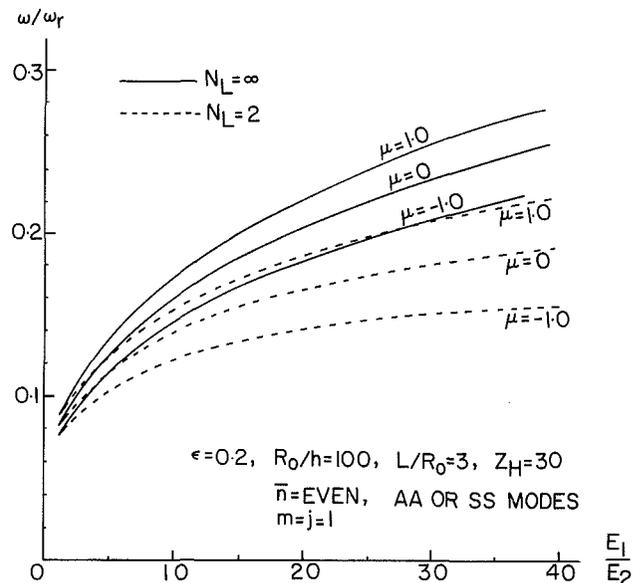


Fig. 4(b) Fundamental frequency versus Young's Moduli ratio for cross-ply Boron-epoxy, simply-supported oval cylindrical shells (SA and AS modes with $\bar{n} = \text{odd}$)

- Culberson, L., and Boyd, D., 1971, "Free Vibrations of Freely Supported Oval Cylinders," *AIAA Journal*, Vol. 9, No. 8, pp. 1474-1480.
- Dongarra, J. J., Bunch, J. R., Moler, C. B., and Stewart, G. W., 1979, "LINPACK Users' Guide," published by the Society for Industrial and Applied Mathematics (SIAM), Philadelphia.
- Du, I. H. Y., and Hui, D., 1986, "Influence of Geometric Imperfections on Vibrations of Antisymmetric Angle-Ply Cylindrical Panels under Combined Loads," *AIAA Journal* (in press).
- Hui, D., Tennyson, R. C., and Hansen, J. S., 1981, "Mode Interaction of Axially Stiffened Cylindrical Shells: Effects of Stringer Axial Stiffness, Torsional Rigidity, and Eccentricity," *ASME JOURNAL OF APPLIED MECHANICS*, Vol. 48, No. 4, pp. 915-922.
- Hui, D., and Hansen, J. S., 1982, "Effect of Stringer Torsional Rigidity on Buckling and Integrally Stiffened Angle Ply Plates," *Fibre Science and Technology*, Vol. 16, January, pp. 39-42.
- Hui, D., and Leissa, A. W., 1983, "Effects of Uni-Directional Geometric Imperfections on Vibrations of Pressurized Shallow Spherical Shells," *Int. J. of Non-Linear Mechanics*, Vol. 18, No. 4, pp. 279-285.
- Hui, D., 1983, "Large Amplitude Vibrations of Geometrically Imperfect Shallow Spherical Shells with Structural Damping," *AIAA Journal*, Vol. 21, No. 12, pp. 1736-1741.

- Hui, D., 1984, "Influence of Geometric Imperfections and In-Plane Constraints on Nonlinear Vibrations of Simply Supported Cylindrical Panels," *ASME JOURNAL OF APPLIED MECHANICS*, Vol. 51, No. 2, pp. 383-390.
- Hui, D., 1985a, "Effects of Geometric Imperfections on Frequency-Load Interaction of Biaxially Compressed Anti-Symmetric Angle Ply Rectangular Plates," *ASME JOURNAL OF APPLIED MECHANICS*, Vol. 52, No. 1, pp. 155-162.
- Hui, D., 1985b, "Soft-Spring Nonlinear Vibrations of Antisymmetrically Laminated Rectangular Plates," *Int. J. of Mechanical Sciences*, Vol. 27, No. 6, pp. 397-408.
- Hui, D., 1986, "Imperfection Sensitivity of Axially Compressed Laminated Flat Plates due to Bending-Stretching Coupling," *Int. J. of Solids and Structures*, Vol. 22, No. 1, pp. 13-22.
- Hutchinson, J. W., 1968, "Buckling and Initial Post-Buckling Behavior of Oval Cylindrical Shells under Axial Compression," *ASME JOURNAL OF APPLIED MECHANICS*, Vol. 35, No. 1, pp. 66-72.
- Kapania, R. K., and Yang, T. Y., 1986, "Buckling, Postbuckling and Nonlinear Vibration of Imperfect Laminated Plates," *Nonlinear Analysis and NDE of Composite Material Vessels and Components*, ASME Publication P-119-ND-3, Hui, D., Duke, J. C., and Chung, H., eds., Chicago, July 20-24, 1986.
- Koumoussis, V. K., and Armenakas, A. E., 1983, "Free Vibrations of Simply Supported Cylindrical Shells of Oval Cross-Section," *AIAA Journal*, Vol. 21, No. 7, pp. 1017-1027.
- Koval'chuk, P. S., and Krasnopol'skaya, T. S., 1980, "Resonance Phenomena in Nonlinear Vibrations of Cylindrical Shells with Initial Imperfections," *Soviet Applied Mechanics*, Mar., pp. 867-872 (translated from *Prikladnaya Mekhanika*, Vol. 15, No. 9, 1979, pp. 100-107).
- Malkina, R. L., 1967, "Vibration of Noncircular Cylindrical Shells," NASA N67-13085, Lockheed translation, Jan.
- Rosen, A., and Singer, J., 1974, "Effect of Axisymmetric Imperfections on the Vibrations of Cylindrical Shells under Axial Compression," *AIAA Journal*, Vol. 12, pp. 995-997.
- Rosen, A., and Singer, J., 1976, "Influence of Asymmetric Imperfections on the Vibrations of Axially Compressed Cylindrical Shells," *Israel Journal of Technology*, Vol. 14, pp. 23-36.
- Sathyamoorthy, M., and Pandalai, K. A. V., 1970, "Nonlinear Flexural Vibrations of Orthotropic Oval Cylindrical Shells," Indian Institute of Technology & Dept. of Astronautical Engrg., Madras, Report, pp. 47-74 (available from Prof. M. Sathyamoorthy of Clarkson Univ., N.Y.).
- Singer, J., and Prucz, J., 1982, "Influence of Initial Geometrical Imperfections on Vibrations of Axially Compressed Stiffened Cylindrical Shells," *J. of Sound and Vibration*, Vol. 80, No. 1, pp. 117-143.
- Sewell, J. L., Thompson, W. M., and Pusey, C. G., 1971, "An Experimental and Analytical Vibration Study on Elliptical Cylindrical Shells," NASA TN D-6089, Feb.
- Soldatos, K. P., Tzivanidis, G. J., 1982, "Buckling and Vibration of Cross-Ply Laminated Non-Circular Cylindrical Shells," *J. of Sound and Vibration*, Vol. 82, No. 32, pp. 425-434.
- Soldatos, K. P., 1983, "Equivalence of Some Methods used for the Dynamic Analysis of Cross-Ply Laminated Oval Cylindrical Shells," *J. of Sound and Vibration*, Vol. 91, No. 3, pp. 461-465.
- Soldatos, K. P., 1984, "A Flugge-Type Theory for the Analysis of Anisotropic Laminated Non-Circular Cylindrical Shells," *Int. J. of Solids and Structures*, Vol. 20, No. 2, pp. 107-120.
- Soldatos, K. P., 1985, "On Thickness Shear Deformation Theories for the Dynamic Analysis of Non-Circular Cylindrical Shells," *Developments in Mechanics*, Vol. 13, Proc. of 19th Midwestern Mechanics Conference, Advani, S. H., Leissa, A. W., and Popelar, C. H., eds., pp. 353-354.
- Suzuki, K., and Leissa, A. W., 1985, "Free Vibrations of Noncircular Cylindrical Shells having Circumferentially Varying Thickness," *ASME JOURNAL OF APPLIED MECHANICS*, Vol. 52, pp. 149-154.
- Tennyson, R. C., Chan, K. H., and Muggeridge, D. B., 1971, "The Effect of Axisymmetric Shape Imperfections on the Buckling of Laminated Anisotropic Circular Cylinders," *Canadian Aeronautics and Space Institute (CASI) Transactions*, Vol. 4, No. 2, Sept., pp. 131-139.
- Watawala, L., and Nash, W., 1983, "Influence of Initial Geometric Imperfections on Vibrations of Thin Circular Cylindrical Shells," *Computers and Structures*, Vol. 16, No. 1-4, pp. 125-130.
- Yang, T. Y., and Kapania, R. K., 1985, "A Finite Element of Nonlinear Vibrations for Imperfect Shells," *Developments in Mechanics*, Vol. 13, Proc. of the 19th Midwestern Mechanics Conference, Advani, S. H., Leissa, A. W., and Popelar, C. H., eds., pp. 432-433.